Printed Pages - 4

Roll No.:....

337831(37)

B. E. (Eighth Semester) Examination, Nov.-Dec. 2021

(New Scheme)

(Mechanical Engg. Branch)

ROBOTICS

Time Allowed: Three hours

Maximum Marks: 80

Minimum Pass Marks: 28

Note: Attempt all questions. Part (a) of each question is compulsory. Attempt any two parts from (b), (c) and (d). Give neat and clear diagrams whenever needed.

Unit-I

1. (a) Write laws of Robotics.

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(b) Classify robots on the bases of Workspace geometry. Explain any one with neat sketch.

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(c)	Explain in brief what are the design and control	
	issue in robotics.	7
(d)	Write short notes on any two:	7
	(i) Work Volume (ii) Load carrying capacity	
	(iii) End Effector	
	Unit-II	
(a)	What do you mean by mapping in robotics?	2
(b)	Derive the fundamental rotation matrices about x, y	
	and z axis that is used to perform a rotation in	
	fundamental space of classical geometry.	7
(c)	What is meant by homogeneous coordinate system	
	for manipulator?	7
(d)	Write about different types of transformations and	
	explain them briefly.	7
	Unit-III	

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3.	(a)	Draw a 3-DOF manipulator arm and show	
		numbering of links and joints.	2
	(b)	Explain DENAVIT HARTENBERG NOTATION.	7
	(c)	Give brief introduction of inverse kinematic model.	7
	(d)	Consider any manipulator of three degree of	
		freedom and derive transformation matrix for it.	7
		Unit-IV	
4.	(a)	What are the basic guidelines for choosing the right	
		sensors?	2
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	(b)	Explain various kinds of sensors used in robotics	
		with suitable diagram and example.	7
	(c)	Write a note on image processing. Also explain	
		monochrome image and digital image.	7
	(d)	Write short notes on any two:	7
		(i) Architecture of Robotic Vision System	
		(ii) Image acquisition in robotics	
		(iii) Template matching	

Unit-V

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5.	(a)	Write about Dull, Dirty, Dangerous and Dear (four
		D's) in robotics
	(b)	Write about applications of robots in industrial
		inspection and testing.
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	(c)	Write about various material handling tasks performed
		by robots in industries.
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	(d)	Write short notes on any two:
		(i) Upcoming future of robots
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		(ii) Robot safety
		(iii) Non industrial application of Robots.
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